# Introduction to higher-order model-checking 

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## What is model-checking?

## The halting problem

A natural question: does a program always terminate?

Undecidable problem (Turing 1936): a machine can not always determine the answer.

What if we use approximations?

## Model-checking

Approximate the program $\longrightarrow$ build a model $\mathcal{M}$.

Then, formulate a logical specification $\varphi$ over the model.

Aim: design a program which checks whether

$$
\mathcal{M} \vDash \varphi
$$

That is, whether the model $\mathcal{M}$ meets the specification $\varphi$.

## An example

| Main | $=$ Listen Nil |
| ---: | :--- |
| Listen $x$ | $=$ |
| if end_signal() then $x$ |  |
|  | else Listen received_data() :: $x$ |

## An example

| Main | $=$ | Listen Nil |
| :---: | :---: | :---: |
| Listen $x$ | $=$ | if end_signal () then $x$ |
|  |  | else Listen received_da |



We abstracted conditionals and datatypes.
The approximation contains a non-terminating branch.

## Finite representations of infinite trees


is not regular: it is not the unfolding of a finite graph as


## Finite representations of infinite trees


but it is represented by a higher-order recursion scheme (HORS).

# Higher-order recursion schemes 

Some regularity for infinite trees

## Higher-order recursion schemes

$$
\begin{aligned}
\text { Main } & =\begin{array}{l}
\text { Listen Nil } \\
\text { Listen } x
\end{array}=\begin{array}{l}
\text { if end_signal() then } x \\
\end{array} \quad \text { else Listen received_data() :: } x
\end{aligned}
$$

is abstracted as

$$
\mathcal{G}= \begin{cases}\mathrm{S} & =\mathrm{LNil} \\ \mathrm{~L} x & =\text { if } x(\mathrm{~L}(\operatorname{data} x))\end{cases}
$$

which represents the higher-order tree of actions


## Higher-order recursion schemes

$$
\mathcal{G}=\left\{\begin{array}{l}
\mathrm{S}=\mathrm{L} N i l \\
\mathrm{~L} x=\text { if } x(\mathrm{~L}(\operatorname{data} x))
\end{array}\right.
$$

Rewriting starts from the start symbol S:


Higher-order recursion schemes

$$
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$$



Higher-order recursion schemes

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\mathcal{G}= \begin{cases}\mathrm{S} & =\mathrm{LNil} \\ \mathrm{~L} x & =\text { if } \times(\mathrm{L}(\operatorname{data} x))\end{cases}
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HORS can alternatively be seen as simply-typed $\lambda$-terms with simply-typed recursion operators $Y_{\sigma}:(\sigma \rightarrow \sigma) \rightarrow \sigma$.

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HORS can alternatively be seen as simply-typed $\lambda$-terms with simply-typed recursion operators $Y_{\sigma}:(\sigma \rightarrow \sigma) \rightarrow \sigma$.

# Alternating parity tree automata 

Checking specifications over trees

## (see Chapter 2)

## Monadic second order logic

MSO is a common logic in verification, allowing to express properties as: «all executions halt»
«a given operation is executed infinitely often in some execution»
<every time data is added to a buffer, it is eventually processed»

## Alternating parity tree automata

Checking whether a formula holds can be performed using an automaton.

For an MSO formula $\varphi$, there exists an equivalent $\mathrm{APT} \mathcal{A}_{\varphi}$ s.t.

$$
\langle\mathcal{G}\rangle \vDash \varphi \quad \text { iff } \quad \mathcal{A}_{\varphi} \text { has a run over }\langle\mathcal{G}\rangle .
$$

APT $=$ alternating tree automata $($ ATA $)+$ parity condition.

## Alternating tree automata

ATA: non-deterministic tree automata whose transitions may duplicate or drop a subtree.

Typically: $\delta\left(q_{0}\right.$, if $)=\left(2, q_{0}\right) \wedge\left(2, q_{1}\right)$.

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Nil data

data


Nil


## Alternating parity tree automata

Each state of an APT is attributed a color

$$
\Omega(q) \in C o l \subseteq \mathbb{N}
$$

An infinite branch of a run-tree is winning iff the maximal color among the ones occuring infinitely often along it is even.


## Alternating parity tree automata

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An infinite branch of a run-tree is winning iff the maximal color among the ones occuring infinitely often along it is even.

A run-tree is winning iff all its infinite branches are.

For a MSO formula $\varphi$ :
$\mathcal{A}_{\varphi}$ has a winning run-tree over $\langle\mathcal{G}\rangle \quad$ iff $\quad\langle\mathcal{G}\rangle \vDash \varphi$.

## The higher-order model-checking problems

The (local) HOMC problem
Input: HORS $\mathcal{G}$, formula $\varphi$.
Output: true if and only if $\langle\mathcal{G}\rangle \vDash \varphi$.

Example: $\varphi=$ 《 there is an infinite execution »


## The (local) HOMC problem

Input: $\operatorname{HORS} \mathcal{G}$, formula $\varphi$.
Output: true if and only if $\langle\mathcal{G}\rangle \vDash \varphi$.

Example: $\varphi=$ 《 there is an infinite execution»


Output: true.

## The global HOMC problem

Input: HORS $\mathcal{G}$, formula $\varphi$.

Output: a HORS $\mathcal{G}^{\bullet}$ producing a marking of $\langle\mathcal{G}\rangle$.

Example: $\varphi=$ « there is an infinite execution »

Output: $\mathcal{G}^{\bullet}$ of value tree:


## The selection problem

Input: HORS $\mathcal{G}$, APT $\mathcal{A}$, state $q \in Q$.
Output: false if there is no winning run of $\mathcal{A}$ over $\langle\mathcal{G}\rangle$. Else, a HORS $\mathcal{G}^{q}$ producing a such a winning run.

Example: $\varphi=$ «there is an infinite execution», $q_{0}$ corresponding to $\varphi$
Output: $\mathcal{G}^{q_{0}}$ producing

$$
\begin{aligned}
& \text { if } q_{0} \\
& \text { if } q_{0} \\
& \text { if }_{1} q_{0}
\end{aligned}
$$

## Purpose of my thesis

These three problems are decidable, with elaborate proofs (often) relying on semantics.

Our contribution: an excavation of the semantic roots of HOMC, at the light of linear logic, leading to refined and clarified proofs.

# Recognition by homomorphism 

Where semantics comes into play

## Automata and recognition

For the usual finite automata on words: given a regular language $L \subseteq A^{*}$, there exists a finite automaton $\mathcal{A}$ recognizing $L$
if and only if. . .

there exists a finite monoid $M$, a subset $K \subseteq M$ and a homomorphism $\varphi: A^{*} \rightarrow M$ such that $L=\varphi^{-1}(K)$.

## Automata and recognition

The picture we want:

## Terms <br> Domain


(after Aehlig 2006, Salvati 2009)
but with recursion and w.r.t. an APT.

# Intersection types and alternation 

A first connection with linear logic

## Alternating tree automata and intersection types

A key remark (Kobayashi 2009):

$$
\delta\left(q_{0}, \text { if }\right)=\left(2, q_{0}\right) \wedge\left(2, q_{1}\right)
$$

can be seen as the intersection typing

$$
\text { if }: \emptyset \rightarrow\left(q_{0} \wedge q_{1}\right) \rightarrow q_{0}
$$

refining the simple typing

$$
\text { if : } 0 \rightarrow 0 \rightarrow 0
$$

## Alternating tree automata and intersection types

In a derivation typing the tree if $T_{1} T_{2}$ :

Intersection types naturally lift to higher-order - and thus to $\mathcal{G}$, which finitely represents $\langle\mathcal{G}\rangle$.

Theorem (Kobayashi 2009)
$\vdash \mathcal{G}: q_{0} \quad$ iff the $A T A \mathcal{A}_{\varphi}$ has a run-tree over $\langle\mathcal{G}\rangle$.

## A closer look at the Application rule

In the intersection type system:

$$
\text { App } \frac{\Delta \vdash t:\left(\theta_{1} \wedge \cdots \wedge \theta_{n}\right) \rightarrow \theta \quad \Delta_{i} \vdash u: \theta_{i}}{\Delta, \Delta_{1}, \ldots, \Delta_{n} \vdash t u: \theta}
$$

## This rule could be decomposed as:

## A closer look at the Application rule

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$$

This rule could be decomposed as:

$$
\frac{\Delta \vdash t:\left(\bigwedge_{i=1}^{n} \theta_{i}\right) \rightarrow \theta^{\prime} \quad \frac{\Delta_{i} \vdash u: \theta_{i} \quad \forall i \in\{1, \ldots, n\}}{\Delta_{1}, \ldots, \Delta_{n} \vdash u: \bigwedge_{i=1}^{n} \theta_{i}}}{\Delta, \Delta_{1}, \ldots, \Delta_{n} \vdash t u: \theta^{\prime}}
$$

## A closer look at the Application rule

$$
\begin{aligned}
& \left.\theta_{i}\right) \rightarrow \theta^{\prime} \\
& \Delta, \Delta_{1}, \ldots, \Delta_{n} \vdash t u: \theta^{\prime} \\
& \Delta_{1}, \ldots, \Delta_{n} \vdash u: \bigwedge_{i=1}^{n} \theta_{i} \\
& \hline, \theta_{i}
\end{aligned}
$$

Linear decomposition of the intuitionistic arrow:

$$
A \Rightarrow B=!A \multimap B
$$

Two steps: duplication / erasure, then linear use.

Right $\bigwedge$ corresponds to the Promotion rule of indexed linear logic. (see G.-Melliès, ITRS 2014)

## Intersection types and semantics of linear logic

$$
A \Rightarrow B=!A \multimap B
$$

Two interpretations of the exponential modality:

Qualitative models (Scott semantics)
$!A=\mathcal{P}_{\text {fin }}(A)$
$\llbracket o \Rightarrow o \rrbracket=\mathcal{P}_{\text {fin }}(Q) \times Q$
$\left\{q_{0}, q_{0}, q_{1}\right\}=\left\{q_{0}, q_{1}\right\}$
Order closure

Quantitative models
(Relational semantics)
! $A=\mathcal{M}_{\text {fin }}(A)$
$\llbracket o \Rightarrow o \rrbracket=\mathcal{M}_{\text {fin }}(Q) \times Q$
$\left[q_{0}, q_{0}, q_{1}\right] \neq\left[q_{0}, q_{1}\right]$
Unbounded multiplicities

## An example of interpretation

In Rel, one denotation:

$$
\left(\left[q_{0}, q_{1}, q_{1}\right],\left[q_{1}\right], q_{0}\right)
$$

In ScottL, a set containing the principal type

$$
\begin{aligned}
& \qquad\left(\left\{q_{0}, q_{1}\right\},\left\{q_{1}\right\}, q_{0}\right) \\
& \text { but also } \\
& \left(\left\{q_{0}, q_{1}, q_{2}\right\},\left\{q_{1}\right\}, q_{0}\right) \\
& \text { and } \\
& \left(\left\{q_{0}, q_{1}\right\},\left\{q_{0}, q_{1}\right\}, q_{0}\right) \\
& \text { and } \ldots
\end{aligned}
$$

## Intersection types and semantics of linear logic


(Bucciarelli-Ehrhard 2001, de Carvalho 2009, Ehrhard 2012, Terui 2012)
Fundamental idea:

$$
\llbracket t \rrbracket \cong\{\theta \mid \emptyset \vdash t: \theta\}
$$

for a closed term.

## Intersection types and semantics of linear logic



Let $t$ be a term normalizing to a tree $\langle t\rangle$ and $\mathcal{A}$ be an alternating automaton.

$$
\mathcal{A} \text { accepts }\langle t\rangle \text { from } q \Leftrightarrow q \in \llbracket t \rrbracket \Leftrightarrow \emptyset \vdash t: q:: \circ
$$

(see Chapter 5)
Extension with recursion and parity condition?

# Adding parity conditions to the type system 

## Alternating parity tree automata

We add coloring annotations to intersection types:

$$
\delta\left(q_{0}, \text { if }\right)=\left(2, q_{0}\right) \wedge\left(2, q_{1}\right)
$$

now corresponds to

$$
\text { if }: \emptyset \rightarrow\left(\square_{\Omega\left(q_{0}\right)} q_{0} \wedge \square_{\Omega\left(q_{1}\right)} q_{1}\right) \rightarrow q_{0}
$$

Idea: if is a run-tree with two holes:


A new neutral (least) color: $\epsilon$.
We refine the approach of Kobayashi and Ong in a modal way (see Chapter $6)$.

## An example of colored intersection type

Set $\Omega\left(q_{0}\right)=0$ and $\Omega\left(q_{1}\right)=1$.

has now type

$$
\square_{0} q_{0} \wedge \square_{1} q_{1} \rightarrow \square_{1} q_{1} \rightarrow q_{1}
$$

Note the color 0 on $q_{0} \ldots$

## A type-system for verification (Grellois-Melliès 2014)

Axiom

$$
\overline{x: \square_{\epsilon} \theta_{i} \vdash x: \theta_{i}}
$$

$$
\begin{gathered}
\delta \quad \frac{\left\{\left(i, q_{i j}\right) \mid 1 \leq i \leq n, 1 \leq j \leq k_{i}\right\} \quad \text { satisfies } \quad \delta_{A}(q, a)}{\emptyset \vdash a: \bigwedge_{j=1}^{k_{1}} \square_{\Omega\left(q_{1 j}\right)} q_{1 j} \rightarrow \ldots \rightarrow \bigwedge_{j=1}^{k_{n}} \square_{\Omega\left(q_{n j}\right)} q_{n j} \rightarrow q} \\
\text { App }
\end{gathered} \frac{\Delta \vdash t:\left(\square_{m_{1}} \theta_{1} \wedge \cdots \wedge \square_{m_{k}} \theta_{k}\right) \rightarrow \theta \quad \Delta \quad \Delta_{i} \vdash u: \theta_{i}}{\Delta+\square_{m_{1}} \Delta_{1}+\ldots+\square_{m_{k}} \Delta_{k} \vdash t u: \theta}
$$

$$
\lambda \quad \frac{\Delta, x: \bigwedge_{i \in I} \square_{m_{i}} \theta_{i} \vdash t: \theta}{\Delta \vdash \lambda x \cdot t:\left(\bigwedge_{i \in I} \square_{m_{i}} \theta_{i}\right) \rightarrow \theta}
$$

$$
\text { fix } \frac{\Gamma \vdash \mathcal{R}(F): \theta}{F: \square_{\epsilon} \theta \vdash F: \theta}
$$

## A type-system for verification

A colored Application rule:

App $\frac{\Delta \vdash t:\left(\square_{m_{1}} \theta_{1} \wedge \cdots \wedge \square_{m_{k}} \theta_{k}\right) \rightarrow \theta \quad \Delta_{i} \vdash u: \theta_{i}}{\Delta+\square_{m_{1}} \Delta_{1}+\ldots+\square_{m_{k}} \Delta_{k} \vdash t u: \theta}$


## A type-system for verification

A colored Application rule:

$$
\text { App } \frac{\Delta \vdash t:\left(\square_{m_{1}} \theta_{1} \wedge \cdots \wedge \square_{m_{k}} \theta_{k}\right) \rightarrow \theta}{\Delta+\square_{m_{1}} \Delta_{1}+\ldots+\square_{m_{k}} \Delta_{k} \vdash t u: \theta}
$$

inducing a winning condition on infinite proofs: the node

$$
\Delta_{i} \vdash u: \theta_{i}
$$

has color $m_{i}$, others have color $\epsilon$, and we use the parity condition.

## A type-system for verification

We now capture all MSO (see Chapter 6-8):

Theorem (G.-Melliès 2014, from Kobayashi-Ong 2009)
$S: q_{0} \vdash S: q_{0}$ admits a winning typing derivation iff the alternating parity automaton $\mathcal{A}$ has a winning run-tree over $\langle\mathcal{G}\rangle$.

We obtain decidability by considering idempotent types.
Our reformulation

- shows the modal nature of $\square$ (in the sense of S4),
- internalizes the parity condition,
- paves the way for semantic constructions.


## Colored models of linear logic

## A closer look at the Application rule

$$
\frac{\Delta \vdash t:\left(\square_{m_{1}} \theta_{1} \wedge \cdots \wedge \square_{m_{k}} \theta_{k}\right) \rightarrow \theta \quad \Delta_{i} \vdash u: \theta_{i}}{\Delta+\square_{m_{1}} \Delta_{1}+\ldots+\square_{m_{k}} \Delta_{k} \vdash t u: \theta}
$$

could be decomposed as:

$$
\frac{\Delta \vdash t:\left(\bigwedge_{i=1}^{k} \square_{m_{i}} \theta_{i}\right) \rightarrow \theta \frac{\Delta_{1} \vdash u: \theta_{1}}{\frac{\square_{m_{1}} \Delta_{1} \vdash u: \square_{m_{1}} \theta_{1}}{\theta} \quad \ldots} \frac{\square_{k} \vdash u: \theta_{k}}{\square_{m_{k}} \Delta_{k} \vdash u: \square_{m_{k}} \theta_{k}}}{} \text { Right } \square \text { Right } \Lambda
$$

Right $\square$ looks like a promotion. In linear logic:

$$
A \Rightarrow B=!\square A \multimap B
$$

We show that the modality $\square$ distributes over the exponential in the semantics.

## Colored semantics

We extend:

- Rel with countable multiplicities, coloring and an inductive-coinductive fixpoint (Chapter 9)
- ScottL with coloring and an inductive-coinductive fixpoint (Chapter 10).

Methodology: think in the relational semantics, and adapt to the Scott semantics using Ehrhard's 2012 result:
the finitary model ScottL is the extensional collapse of Rel.

## Infinitary relational semantics

Extension of Rel with infinite multiplicities:

$$
\dot{z} A=\mathcal{M}_{\text {count }}(A)
$$

and coloring modality (parametric comonad)

$$
\square A=\operatorname{Col} \times A
$$

Composite comonad: $\downarrow=z \square$ is an exponential.
Induces a colored CCC Rel ( $\rightarrow$ model of the $\lambda$-calculus).

An example of interpretation
Set $\Omega\left(q_{i}\right)=i$.

has denotation
$\left(\left[\left(0, q_{0}\right),\left(1, q_{1}\right),\left(1, q_{1}\right)\right],\left[\left(1, q_{1}\right)\right], q_{1}\right)$
(corresponding to the type $\square_{0} q_{0} \wedge \square_{1} q_{1} \rightarrow \square_{1} q_{1} \rightarrow q_{1}$ )

## Model-checking and infinitary semantics

Inductive-coinductive fixpoint operator: composes denotations w.r.t. the parity condition.

Theorem
An APT $\mathcal{A}$ has a winning run from $q_{0}$ over $\langle\mathcal{G}\rangle$ if and only if

$$
q_{0} \in \llbracket \lambda(\mathcal{G}) \rrbracket_{\mathcal{A}}
$$

where $\lambda(\mathcal{G})$ is a $\lambda Y$-term corresponding to $\mathcal{G}$.

## Conjecture

An APT $\mathcal{A}$ has a winning run from $q_{0}$ over $\langle\mathcal{G}\rangle$ if and only if

$$
q_{0} \in \llbracket \lambda(\mathcal{G})^{\Sigma} \rrbracket \circ \llbracket \delta^{\dagger} \rrbracket
$$

where $\lambda(\mathcal{G})^{\Sigma}$ is a Church encoding of a $\lambda Y$-term corresponding to $\mathcal{G}$.

## Finitary semantics

In ScottL, we define $\square, \lambda$ and $\mathbf{Y}$ similarly (using downward-closures). ScottL $L_{b}$ is a model of the $\lambda Y$-calculus.

Theorem
An APT $\mathcal{A}$ has a winning run from $q_{0}$ over $\langle\mathcal{G}\rangle$ if and only if

$$
q_{0} \in \llbracket \lambda(\mathcal{G}) \rrbracket .
$$

## Corollary

The local higher-order model-checking problem is decidable (and is $n$-EXPTIME complete).

## Theorem

The selection problem is decidable.

## Perspectives

- A purely coinductive proof of the soundness-and-completeness theorem
- Accommodating the modal approach to other classes of automata
- Understanding the infinitary semantics
- Logical aspects: colored tensorial logic, fixpoints...
- Game semantics interpretations?
- Is the complexity related to light linear logics?
- Extensional collapse between the two colored models?

